

## Matrix Completion

- 1 -

Předpokládejme, že  $A \in \mathbb{R}^{n \times m}$  je matice s nulačkou hodnotou  
 $(\text{rank}(A) = r < m)$ .

Z tego mamy pozwolenie jaka caść...  $\{X_1, \dots, X_{n^2}\}$  jest

ortonormal basis  $(\mathbb{R}^{m \times n}, \| \cdot \|_F)$  a

$$A = \sum_{a=1}^{m^2} \langle X_a, A \rangle_F \cdot X_a \quad (*)$$

My porojective jen  $\{\langle x_a, A \rangle\}_{F^a \in S_2}$ , kde  $S \subset \{l_1, m^2\}$

Pokusíme se rekonstruovat A z této informace

$$\arg \min_{Z \in \mathbb{R}^{m \times m}} \|Z\|_* \text{ s.t. } \langle X_{w_j}, Z \rangle = \langle X_{w_j}, A \rangle_F \quad (P_*)$$

$j=1, \dots, m; \Omega = \{w_1, \dots, w_m\}$

Poznámej. A budeme pridat samoadj.  $X$  a obecně ne  
 $\downarrow$ .  $X_i$ 's jsou ek.  $e_i^T \dots$  matices I na místech (k, l), jinde

$$k, l = l_1, \dots, m \quad \langle X_i, A \rangle_F = \langle e_k \cdot e_l^T, A \rangle = A_{k,l}$$

... vidíme je nekteré prvky A.

- Chceu  $\Delta m$  co nejmenší  $n \left\{ \begin{array}{|c|c|} \hline & \\ \hline \end{array} \right\}$  L.b.  $\rightarrow n \cdot m + (n-r) \cdot r = 2nm - r^2$  parametru

- $\|Z\|_* = \sum_{j=1}^m |\lambda_j(Z)|$  je mukleapre' norma

- Oznacíme: Pro  $w = 1, \dots, m^2$  je  $X_w$  jedna prvek báze -2-
- Pro  $w$  mat. veličinu souboru hodnot  $w \in \{1, \dots, m^2\}$   
je  $X_w$  mat. matice a

$$P_w : \mathbb{Z} \rightarrow \langle X_w, \mathbb{Z} \rangle_F X_w$$

je matodlný operátor ... matodlný projekce

- Vbereme-li m mat. členů řešení, sopa koeficientu  $\alpha^{(*)}$ , dostaneme

$$Q : \mathbb{Z} \rightarrow \sum_{j=1}^{m^2} \langle X_{wj}, \mathbb{Z} \rangle_F X_{wj}$$

$$\mathbb{E} Q(\mathbb{Z}) = m^2 \cdot \mathbb{E} \langle X_w, \mathbb{Z} \rangle X_w = m^2 \cdot \sum_{k=1}^{m^2} \frac{1}{m^2} \cdot \langle X_k, \mathbb{Z} \rangle X_k = \mathbb{Z}$$

- Uloha je zjistit věrojatelnost např. pro  $A = e_i e_i^T$  &  $X_2$  typu  $\{e_k e_k^T\}_{k=1}^{m^2}$

- $A u_j = \lambda_j u_j$ ;  $\lambda_1, \dots, \lambda_n \neq 0$ ,  $\lambda_{n+1}, \dots, \lambda_m = 0$

$$\begin{aligned} U = \text{range}(A) &= \text{span}\{u_1, \dots, u_n\} \quad A = P_U A = A P_U \\ &= \text{ker}(A)^\perp \quad O = P_{U^\perp} A = A P_{U^\perp} \end{aligned}$$

- $\mathbb{Z} = (P_U + P_{U^\perp}) \mathbb{Z} (P_U + P_{U^\perp})$

- $T := \{\mathbb{Z} : P_{U^\perp} \mathbb{Z} P_{U^\perp} = 0\}$

$$\begin{aligned} P_T \dots \text{projekce na } T \dots P_T(\mathbb{Z}) &= P_U \mathbb{Z} P_U + P_U \mathbb{Z} P_{U^\perp} + P_{U^\perp} \mathbb{Z} P_U \\ &= P_U \mathbb{Z} + \mathbb{Z} P_U - P_U \mathbb{Z} P_U \end{aligned}$$

Definice: Matice  $A \in \mathbb{R}^{m \times n}$  s rank(A)=r má koherenci  $\nu > 0$   
vzhledem k bazi  $\{x_a\}_{a=1}^m$  pokud platí

$$\max_a \|x_a\|^2 \leq \frac{\nu}{n} \quad (K1)$$

nebo

$$\max \|P_T x_a\|_F^2 \leq \frac{2\nu}{n} \quad \& \quad \max_a \left\langle x_a, \text{rgu}(A) \right\rangle_F^2 \leq \frac{2\nu}{n} \quad (K2)$$

Poznámky: •  $\text{rgm}(A) = \mathbb{J}_j$  uvedené  $\text{rgu}(\mathbb{J}_j)$   
 $\text{rgm}(A) u_j = \text{rgu}(\mathbb{J}_j) u_j$

- $\|x_a\|_F = 1$ , tedy  $\|x_a\| \geq \frac{1}{\sqrt{n}}$  ...  $\nu \geq 1$  v (K1)

- matice  $\mathbb{Z}$  mají rank  $\leq 2r$  ... (K1)  $\Rightarrow$  první řádky (K2)

$$\|P_T x_a\|_F^2 = \sup_{\mathbb{Z} \in T, \|\mathbb{Z}\|_F = 1} \left\langle x_a, \mathbb{Z} \right\rangle_F^2 \leq \sup_{\mathbb{Z}} \|x_a\|^2 \cdot \|\mathbb{Z}\|_*^2$$

$$\leq \sup_{\mathbb{Z}} \|x_a\|^2 \cdot (2r \cdot \|\mathbb{Z}\|_F^2) \stackrel{(K1)}{\leq} \frac{2r \cdot \nu}{n}$$

Věta: Nechť  $A$  je  $m \times n$  matice s koherencí  $\nu$  vzhledem k  $\{x_a\}_{a=1}^m$ .

Nechť  $\Omega$  je náhodná podmnožina s  $| \Omega | \geq O(m \nu \nu(1+\beta) \ln^2 n)$ .

Pak řešení ( $\mathbb{P}_*$ ) je jednoznačné a rovno  $\mathbb{Z}$  s  $\mathbb{P} \geq 1 - n^{-\beta}$ .

Důkaz: Pro  $\mathbb{Z} \in \mathbb{R}^{m \times m}$  platí  $\Delta = \mathbb{Z} - A$ . Chceme ukázat, že

$$\|\Delta\|_* = \|\Delta + A\|_* > \|A\|_* \quad \text{pokud je } \left\langle x_{w_j}, \mathbb{Z} \right\rangle_F = \left\langle x_{w_j}, A \right\rangle_F \quad \text{pro } j=1, \dots, |\Omega|$$

... tedy  $R(\mathbb{Z}) = R(A) \dots R(\Delta) = \emptyset$

• Je-li  $R(\Delta) \neq \emptyset \dots$  inflexible ... neexistuje ( $\mathbb{P}_*$ ) ...  $\Delta = \Delta_T + \Delta_{T^\perp}; \Delta = P_T \Delta$ .

Krok 1.: Redukce na matematický sampling s opakováním -4-

- upeček ( $P_*$ ) bleská stínu, jak se zmenšuje počet podlejných

$$\langle X_{w_j}, \mathbb{I} \rangle_F = \langle X_w, A \rangle_F$$

-- Výšší počet podlejných zmenšuje keru ( $\mathcal{Q}$ ) ... zmenšuje počet feasible  $S$  & roste pravd. že  $A$  je opravdu pravé smejm. H. k.  
v. keru ( $\mathcal{Q}$ ) +  $A$

Krok 2.: Uvažujme  $\mathcal{R} = \frac{m}{m^2} \sum_{j=1}^m P_{w_j}$ , w. sampling nedávle.

$$\cdot \mathbb{E} \mathcal{R} = \text{Id}$$

$$\cdot \mathbb{E}[P_T \mathcal{R} P_T] = P_T [\mathbb{E} \mathcal{R}] P_T = P_T$$

$$\cdot označme p_i := \mathbb{P}(\|P_T - P_T \mathcal{R} P_T\| \geq \frac{1}{2})$$

$$\cdot Nechť \|P_T - P_T \mathcal{R} P_T\| \leq \frac{1}{2} \text{ a } \|\Delta_{T^{\perp}}\|_F^2 \geq 2mn^2 \|\Delta_{T^{\perp}}\|_F^2$$

$$\text{Ráž } \|\mathcal{R}(\Delta_{T^{\perp}})\|_F^2 \leq \|\mathcal{R}\|_F^2 \cdot \|\Delta_{T^{\perp}}\|_F^2$$

$$\text{operatorová norma } \mathcal{R}: (\mathbb{R}^{m \times m}, \|\cdot\|_F) \rightarrow (\mathbb{R}^{m \times m}, \|\cdot\|_F) \dots = \frac{m^2}{m} \cdot \text{nejvyšší počet kolizií}$$

$$\leq m^4 \cdot \|\Delta_{T^{\perp}}\|_F^2 \leq \frac{m^4}{2mn^2} \cdot \|\Delta_T\|_F^2 \stackrel{?}{=} \frac{m^2}{m} \cdot \underbrace{(1 - \|P_T - P_T \mathcal{R} P_T\|)}_{\geq \frac{1}{2}} \cdot \|\Delta_T\|_F^2 \stackrel{?}{=} m^2$$

$$\leq \frac{m^2}{m} \left( \langle \Delta_T, \Delta_T \rangle - \langle [P_T - P_T \mathcal{R} P_T] \Delta_T, \Delta_T \rangle \right)$$

$$= \frac{m^2}{m} \left( \langle \Delta_T, \Delta_T \rangle - \langle P_T \Delta_T, \Delta_T \rangle_F + \langle P_T \mathcal{R} P_T \Delta_T, \Delta_T \rangle_F \right)$$

$$= \frac{m^2}{m} \langle \Delta_T, P_T Q P_T \Delta_T \rangle_F = \frac{m^2}{m} \langle \Delta_T, Q \Delta_T \rangle_F$$

$$= \frac{m^2}{m} \left\langle \Delta_T, \underbrace{\frac{m}{m} \sum_{j=1}^m}_{P_{W_j}} P_{W_j}(\Delta_T) \right\rangle = \frac{m^4}{m^2} \sum_{j=1}^m \langle \Delta_T, P_{W_j}(\Delta_T) \rangle$$

$$= \frac{m^4}{m^2} \sum_{j=1}^m \langle P_{W_j}(\Delta_T), P_{W_j}(\Delta_T) \rangle = \frac{m^4}{m^2} \sum_{j,k=1}^m \langle P_{W_j}(\Delta_T), P_{W_k}(\Delta_T) \rangle$$

$$= \langle Q \Delta_T, Q \Delta_T \rangle = \|Q \Delta_T\|^2$$

- tedy  $\|Q(\Delta_T)\|_F^2 < \|Q(\Delta_T)\|_F^2$  &  $Q(\Delta) \neq 0 \dots \Delta_T$  je nesplnitelné.

"Zbyva" odhadnutí  $p_1 := \mathbb{P}(\|P_T - P_T Q P_T\| \geq t) \dots \leq \exp\left(\frac{-t^2 m}{4Bm^2 + 1}\right)$

$$\text{pro } t = \frac{1}{2}$$

$$0 < t < 2$$

Z Beraskinové nerovnosti:

$$S_{W_j} = \frac{m^2}{m} P_T P_{W_j} P_T - \frac{1}{m} P_T$$

$$\cdot E S_{W_j} = \frac{m^2}{m} P_T [E P_{W_j}] P_T - \frac{1}{m} P_T = \frac{m^2}{m} P_T \left[ \underbrace{\frac{1}{m^2} \sum_{a=1}^{m^2} P_{W_a}}_{Id} \right] P_T - \frac{1}{m} P_T$$

$$\sum_{j=1}^{m^2} S_{W_j} = 0$$

$$\cdot \sum_{j=1}^{m^2} S_{W_j} = \frac{m^2}{m} P_T \left[ \sum_{j=1}^{m^2} P_{W_j} \right] P_T - P_T = P_T Q P_T - P_T$$

• Oddhaad  $\|S_{w_j}\|$

$$\|S_{w_j}\| = \left\| \frac{m^2}{m} P_T P_{w_j} P_T - \frac{1}{m} P_T \right\| \leq \frac{m^2}{m} \underbrace{\|P_T P_{w_j} P_T\|}_{\leq 1} + \frac{1}{m} \underbrace{\|P_T\|}_{\leq 1}$$

$$\|P_T P_{w_j} P_T(Z)\|_F = \|P_T(\langle P_T(Z), X_{w_j} \rangle \cdot X_{w_j})\|_F$$

$$= |\langle P_T(Z), X_{w_j} \rangle| \cdot \|P_T(X_{w_j})\|_F = |\langle Z, P_T(X_{w_j}) \rangle| \cdot \|P_T(X_{w_j})\|_F$$

$$\leq \|Z\|_F \cdot \underbrace{\|P_T(X_{w_j})\|_F}_\leq \frac{2\sqrt{n}}{n}$$

$$\leq \frac{m^2}{m} \cdot \frac{2\sqrt{n}}{n} + \frac{1}{m} = \frac{2\sqrt{mn} + 1}{m} = : c$$

•  $V_o^2: \|E[S_{w_j}]^2\| = \|E[(\frac{m^2}{m} P_T P_{w_j} P_T - \frac{1}{m} P_T)^2]\|$

$$= \|E\left(\frac{m^2}{m} P_T P_{w_j} P_T\right)^2 - \underbrace{\frac{2m^2}{m^2} E[P_T P_{w_j} P_T]}_{-\frac{2m^2}{m^2} \cdot \frac{1}{m^2} \text{Id} \cdot P_T} + \frac{1}{m^2} P_T\|$$

$$E P_{w_j} = \frac{1}{m^2} \text{Id}$$

$$= \|E\left(\frac{m^2}{m} P_T P_{w_j} P_T\right)^2 - \frac{1}{m^2} P_T\|$$

$$\leq \frac{m^4}{m^2} \|E[P_T P_{w_j} P_T P_{w_j} P_T]\| + \frac{1}{m^2} .$$

$P_{\omega_j} P_T(Z) \in \text{span}\{X_{\omega_j}\}$  a  $P_{\omega_j} P_T(X_{\omega_j}) = \langle P_T X_{\omega_j}, X_{\omega_j} \rangle X_{\omega_j}$   
... na  $\text{span}\{X_{\omega_j}\}$ , je  $P_{\omega_j} P_T$  točki jiko od.  $\langle P_T X_{\omega_j}, X_{\omega_j} \rangle$

$$\Rightarrow P_T P_{\omega_j} P_T (P_{\omega_j} P_T) = P_T \left\{ \langle P_T X_{\omega_j}, X_{\omega_j} \rangle P_{\omega_j} P_T \right\}$$

$$\Rightarrow \|E[P_T P_{\omega_j} P_T P_{\omega_j} P_T]\| = \|E[\langle P_T X_{\omega_j}, X_{\omega_j} \rangle P_{\omega_j} P_T]\|$$

$$\leq \underbrace{\max_w \langle P_T X_{\omega_j}, P_T X_{\omega_j} \rangle}_{\leq \frac{2m}{n}} \cdot \underbrace{\|E[P_T P_{\omega_j} P_T]\|}_{\frac{1}{m^2} \|P_T\|}$$

$\overline{P_T P_{\omega_j} P_T}$   
je prawoadj.

Alkem  $\|E[S_{\omega_j}]\|^2 \leq \frac{m^4}{m^2} \cdot \frac{2m}{n} \cdot \frac{1}{m^2} \|P_T\|^2 + \frac{1}{m^2} = \frac{2mr_{m+1}}{Vm^2} =: V_0^2$

Pro  $0 < t < \frac{2mV_0^2}{c} = \frac{\text{Lek. } \frac{2mr_{m+1}}{m^2}}{\frac{2mr_{m+1}}{m}} = 2$  je

$$2N \exp\left(-\frac{t^2}{4mV_0^2}\right)$$

$$\mathbb{P}(\|P_T - P_T R P_T\| > t) \leq 2 \cdot N \cdot \exp\left(-\frac{t^2 m^2}{4m(2mr_{m+1})}\right)$$

$$= 2N \exp\left(-\frac{1 \cdot m}{16(2mr_{m+1})}\right) \text{ pro } t = \frac{1}{2}$$

... operator by uverujece def. pravde na T

$$N = \dim T = 2nr - r^2 \leq 2nr$$

$$\therefore P_T \leq 4nr \exp\left(-\frac{m}{16(2mr_{m+1})}\right)$$

Krok 3:  $\Delta_T$  male' ...  $\|\Delta_T\|_F^2 \leq 2m n^2 \|\Delta_{T^\perp}\|_F^2$

... bude stat'  $\|\Delta_T\|_F^2 \leq m^4 \|\Delta_{T^\perp}\|_F^2$

&  $Q(\Delta) = 0$  ... tedy  $\Delta \in \ker(Q)$  ...  $\Delta \in \text{range}(Q)^\perp$

Ukážeme, že pak  $\|Z\|_* = \|A + \Delta\|_* > \|A\|_*$

•  $U := \text{range}(A)$  ✓ posluing ineq.

$$\text{Odhadme } \|A + \Delta\|_* \geq \|P_U(A + \Delta)P_{U^\perp}\|_* + \|P_{U^\perp}(A + \Delta)P_{U^\perp}\|_*$$

$$= \underbrace{\|P_U A P_U + P_U \Delta P_U\|_*}_{= A} + \underbrace{\|P_{U^\perp} A P_{U^\perp} + P_{U^\perp} (\Delta_T + \Delta_{T^\perp}) P_{U^\perp}\|_*}_{= 0}$$

$$= \|A + P_U \Delta P_U\|_* + \|\Delta_{T^\perp}\|_* \quad \Delta_{T^\perp} = P_{T^\perp} \Delta$$

$$\geq \langle \text{pgm}(A), A + P_U \Delta P_U \rangle_F + \underbrace{\|\Delta_{T^\perp}\|_*}_{= P_{U^\perp} \Delta P_{U^\perp}}$$

$$+ \langle \text{pgm}(\Delta_{T^\perp}), \Delta_{T^\perp} \rangle_F$$

$$= \|A\|_* + \langle \text{pgm}(A), P_U \Delta P_U \rangle_F + \langle \text{pgm}(\Delta_{T^\perp}), \Delta_{T^\perp} \rangle_F$$

$$= \|A\|_* + \langle \text{pgm}(A), \Delta \rangle_F + \langle \text{pgm}(\Delta_{T^\perp}), \Delta \rangle_F$$

A vbaší  $\{u_1, \dots, u_m\}$  ...

$$\begin{pmatrix} P_U A P_U & P_U A P_{U^\perp} \\ \hline P_{U^\perp} A P_U & P_{U^\perp} A P_{U^\perp} \end{pmatrix} = \begin{pmatrix} A & 0 \\ 0 & 0 \end{pmatrix}$$

$$\text{pro } \Delta_{T^\perp} : \left( \begin{pmatrix} 0 & 0 \\ 0 & \Delta_{T^\perp} \end{pmatrix} \right)$$

Ukážeme, že  $\langle \text{pgm}(A) + \text{pgm}(\Delta_{T^\perp}), \Delta \rangle_F > 0$  ajsme hotov!

Ukazáváme, že  $\exists Y \in \text{range}(A)$ , s

$$\|P_T Y - \text{sgn}(A)\|_F \leq \frac{1}{2n^2} \quad \text{a} \quad \|P_{T^\perp} Y\| \leq \frac{1}{2}$$

... pak  $Y \in \text{ker}(A)^\perp \cap Y, \Delta \geq c$

$$\Rightarrow \langle \text{sgn}(A) + \text{sgn}(\Delta_{T^\perp}), \Delta \rangle_F$$

$$= \langle \text{sgn}(A) + \text{sgn}(\Delta_{T^\perp}) - Y, \Delta \rangle_F$$

$$= \langle \text{sgn}(A) - Y, \Delta_T \rangle + \langle \text{sgn}(\Delta_{T^\perp}) - Y, \Delta_{T^\perp} \rangle_F$$

$$= \underbrace{\langle \text{sgn}(\Delta_{T^\perp}), \Delta_{T^\perp} \rangle_F}_{=\|\Delta_{T^\perp}\|_*} - \underbrace{\langle P_{T^\perp} Y, \Delta_{T^\perp} \rangle_F}_{\leq \frac{1}{2} \|\Delta_{T^\perp}\|_*} - \underbrace{\langle P_T Y - \text{sgn}(A), \Delta_T \rangle}_{\leq \frac{1}{2n^2} \|\Delta_T\|_F}$$

$$\geq \frac{1}{2} \|\Delta_{T^\perp}\|_* - \frac{1}{2n^2} \|\Delta_T\|_F \geq \frac{1}{2} \|\Delta_{T^\perp}\|_F - \frac{1}{2n^2} \|\Delta_T\|_F > 0.$$

Zbyva'': pinching ineq.  
• existence Y

Pinching ineq.:  $\|P_U Z P_U\|_* + \|P_{U^\perp} Z P_{U^\perp}\|_*$

$$= \sup_{\|A\| \leq 1} \langle P_U Z P_U, A \rangle_F + \sup_{\|B\| \leq 1} \langle P_{U^\perp} Z P_{U^\perp}, B \rangle$$

$$= \sup_{\|A\| \leq 1} \langle Z, P_U A P_U \rangle + \sup_{\|B\| \leq 1} \langle Z, P_{U^\perp} B P_{U^\perp} \rangle$$

$$= \sup_{\|A\| \leq 1, \|B\| \leq 1} \langle Z, P_U A P_U + P_{U^\perp} B P_{U^\perp} \rangle$$

$$\leq \sup_{\|C\| \leq 1} \langle Z, C \rangle_F = \|Z\|_*$$

Existence  $\tilde{Y}$  ... da podmínky (K1) -- jinak v původním -10- cíleku

- $\tilde{Y} \in \text{Range}(R)$
- $\|P_T \tilde{Y} - \text{sgn}(A)\|_F \leq \frac{1}{2m^2}$
- $\|P_{T^\perp} \tilde{Y}\| \leq \frac{1}{2}$

$P_T \tilde{Y}$  má být blízko  $\text{sgn}(A)$  ... logická volba by byla

$$\tilde{Y} := \frac{m^2}{m} \sum_{i=1}^m \langle X_{w_i}, \text{sgn}(A) \rangle_F \cdot X_{w_i} = R(\text{sgn}(A))$$

- konverguje pomalu  $\Rightarrow$  Goffing schéma

Předpis  $\tilde{Y}_1 := \frac{m^2}{k} \sum_{i=1}^k \langle X_{w_i}, \text{sgn}(A) \rangle X_{w_i}$

$$\tilde{Y}_2 := \tilde{Y}_1 + \frac{m^2}{k} \sum_{i=k+1}^{2k} \langle X_{w_i}, \text{sgn}(A) - P_T \tilde{Y}_1 \rangle X_{w_i}$$

... konverguje exp. rychle v  $\ell = \frac{m^2}{k}$

Lemma: Pro ZET platí

$$\mathbb{P}(\|P_{T^\perp} R(Z)\| > t) \leq \begin{cases} 2n \exp\left(-\frac{t^2 m}{4\sqrt{n} \|Z\|_F^2}\right), & t \leq \sqrt{2n} \|Z\|_F \\ 2n \exp\left(-\frac{t m}{2\sqrt{2n} \|Z\|_F}\right), & t > \sqrt{2n} \|Z\|_F \end{cases}$$

Rozdělení  $m = m_1 + \dots + m_r$  a definice

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$$R_i : \mathbb{Z} \rightarrow \frac{\mathbb{Z}}{m_i} \sum_{j=w_{i-1}+1}^{w_i+m_i} \langle X_{w_j}, \mathbb{Z} \rangle_F X_{w_j}$$

$$Y_0 := 0 ; Z_0 = \text{sgn}(A)$$

$$Y_i := Y_{i-1} + R_i(Z_{i-1}) = \sum_{j=1}^i R_j(Z_{j-1})$$

$$Z_i := \text{sgn}(A) - P_T Y_i$$

$Y_i$  ... i-tá iterace

$Z_i$  ... ohýba i-hé iterace

$$\text{Pak } Z_0 := \text{sgn}(A)$$

$$Z_1 = \text{sgn}(A) - P_T Y_1 = \text{sgn}(A) - P_T R_1 \text{sgn}(A) = (\text{Id} - P_T R_1 P_T) \text{sgn}(A)$$

$$Z_2 = \text{sgn}(A) - P_T(Y_2) = \text{sgn}(A) - P_T(Y_1 + R_2 Z_1) =$$

$$= \text{sgn}(A) - P_T(R_1 P_T \text{sgn}(A)) + R_2(\text{Id} - P_T R_1 P_T) \text{sgn}(A)$$

$$= (\text{Id} - P_T R_1 P_T) \text{sgn}(A) - P_T R_2 (\text{Id} - P_T R_1 P_T) \text{sgn}(A)$$

$$= (\text{Id} - P_T R_2 P_T)(\text{Id} - P_T R_1 P_T) \text{sgn}(A)$$

$$\text{deči } Z_i = (\text{Id} - P_T R_i P_T) \dots (\text{Id} - P_T R_1 P_T) \text{sgn}(A)$$

$\Rightarrow P = P_i(i)$  nechť je pláh'  $\|(\text{Id} - P_T R_i P_T)\| \leq \frac{1}{2}$  ... prob. of řešení

$$\|Z_i\|_F = \|(\text{Id} - P_T R_i P_T) Z_{i-1}\|_F \leq \frac{1}{2} \|Z_{i-1}\|_F$$

$$\|Z_0\|_F = \sqrt{r}$$

$$\text{pak } \|Z_i\|_F \leq \frac{\sqrt{r}}{2^i}$$

- $\Rightarrow$  prob. of failure  $P_3(\cdot)$

$$\|P_T \mathcal{R}_i Z_{i-1}\| \leq \frac{1}{4\sqrt{n}} \|Z_{i-1}\|_F$$

$$\begin{aligned} \|\mathcal{P}_T \tilde{\ell}\| &= \left\| P_T \left( \sum_{j=1}^{\ell} Q_j Z_{j-1} \right) \right\| \leq \sum_{j=1}^{\ell} \|P_T Q_j Z_{j-1}\| \leq \frac{1}{4\sqrt{n}} \sum_{j=1}^{\ell} \|Z_{j-1}\|_F \\ &\leq \frac{1}{4\sqrt{n}} \sum_{j=1}^{\ell} \frac{\sqrt{n}}{2^{j-1}} \leq \frac{1}{4} \cdot \left( \frac{1}{2} + \frac{1}{4} + \dots \right) = \frac{1}{2}. \end{aligned}$$

$a \quad \|Z_\ell\| = \|\mathcal{P}_T \tilde{\ell} - \text{sgn}(A)\| \leq \frac{\sqrt{n}}{2^\ell} \leq \frac{1}{2m} \quad \text{pro } \ell = \text{Flag}_2(2m^2\sqrt{n})$

... vlastnosti (ii) & (iii)  
producl certificate  $\mathcal{T}$  ... (i) je jasna!

Zbytná lemma & důkaz, že  $P_1 + \sum_{i=1}^{\ell} P_2(i) + \sum_{i=1}^{\ell} P_3(i) \leq m^{-\beta}$ .

•  $P_1 = 4mn \exp\left(-\frac{m}{16(2m+n)}\right)$

•  $P_2: \mathbb{P}\left(\|\mathcal{P}_T - \mathcal{P}_T \mathcal{R}_i \mathcal{P}_T\| \geq \frac{1}{2}\right) \leq 4mn \exp\left(-\frac{m_i}{16G\sqrt{nm+1}}\right) = P_2(i)$

•  $P_3$  ... lemma:  $\mathbb{P}\left(\|\mathcal{P}_T \mathcal{R}_i Z_{i-1}\| > \frac{\|Z_i\|_F}{4\sqrt{n}}\right) \leq 2n \exp\left(-\frac{\|Z_i\|_F^2 / 16n \cdot m_i}{4mn \cdot \|Z_{i-1}\|_F^2}\right)$   
 $= 2n \exp\left(-\frac{m_i}{64mn}\right)$

Chancce  $P_1 \leq \frac{m^{-\beta}}{3}$ ;  $P_2 \leq \frac{m^{-\beta}}{3\ell}$ ;  $P_3 \leq \frac{m^{-\beta}}{3\ell}$

$$2: 64mr \exp\left(-\frac{m_i}{16(2mr_{m+1})}\right) \leq m^{-\beta}/3$$

$$12\ell m^{(1+\beta)/2} \leq \exp\left(\frac{m_i}{16(2mr_{m+1})}\right) \dots \ln(12\ell m^{(1+\beta)/2}) \leq \frac{m_i}{16(2mr_{m+1})}$$

$$m_i \geq 16(2mr_{m+1}) \ln(12\ell m^{(1+\beta)/2})$$

$$3: 2n \exp\left(-\frac{m_i}{64mr}\right) \leq \frac{m^{-\beta}}{3\ell} \dots \ln(6\ell m^{1+\beta}) \leq \frac{m_i}{64mr}$$

$$m_i \geq 64mr \ln(6\ell m^{1+\beta})$$

recall:  $\rho = \log(2m^2r)$   
 $\approx \log(n)$

$$\Rightarrow m \geq 64mr \ell \cdot \ln(12\ell m^{1+\beta}/2)$$

$$= O(rmr \cdot \log n \cdot (1+\beta) \log n)$$